


Thermal Infrared Imaging Experiments of C-Type Asteroid 162173 Ryugu on Hayabusa2

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Received: 24 September 2015 / Accepted: 31 August 2016 / Published online: 27 September 2016
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Abstract The thermal infrared imager TIR onboard Hayabusa2 has been developed to investigate thermo-physical properties of C-type, near-Earth asteroid 162173 Ryugu. TIR is one of the remote science instruments on Hayabusa2 designed to understand the nature of a volatile-rich solar system small body, but it also has significant mission objectives to provide information on surface physical properties and conditions for sampling site selection

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as well as the assessment of safe landing operations. TIR is based on a two-dimensional uncooled micro-bolometer array inherited from the Longwave Infrared Camera LIR on Akatsuki (Fukuhara et al., 2011). TIR takes images of thermal infrared emission in 8 to 12 μm with a field of view of $16 \times 12^\circ$ and a spatial resolution of 0.05° per pixel. TIR covers the temperature range from 150 to 460 K, including the well calibrated range from 230 to 420 K. Temperature accuracy is within 2 K or better for summed images, and the relative accuracy or noise equivalent temperature difference (NETD) at each of pixels is 0.4 K or lower for the well-calibrated temperature range. TIR takes a couple of images with shutter open and closed, the corresponding dark frame, and provides a true thermal image by dark frame subtraction. Data processing involves summation of multiple images, image processing including the StarPixel compression (Hihara et al., 2014), and transfer to the data recorder in the spacecraft digital electronics (DE). We report the scientific and mission objectives of TIR, the requirements and constraints for the instrument specifications, the designed instrumentation and the pre-flight and in-flight performances of TIR, as well as its observation plan during the Hayabusa2 mission.

Keywords Thermography · Thermal inertia · Temperature · Near-Earth asteroid · Planetary exploration

1 Introduction

The thermal infrared imager TIR has been developed for Hayabusa2, a sample return mission to C-type near-Earth asteroid 162173 Ryugu (formerly 1999 JU₃), to image the thermal emission of the surface of the asteroid and investigate its surface thermo-physical properties. This thermographic instrument is based on a two-dimensional uncooled micro-bolometer array, inherited from the Longwave Infrared Camera LIR on the Akatsuki (Planet-C) Venus climate orbiter (Fukuhara et al. 2011). Thermal radiometry has been one of the traditional methods in planetary missions to measure temperature and surface physical properties of planetary surfaces, and thermal mapping has been conducted by tracking or scanning the surface from orbit (e.g., Kieffer et al. 1973; Chase et al. 1976; Kieffer et al. 1977; Christensen et al. 2001, 2003; Paige et al. 2009; Hiesinger and Helbert 2010). Recent progress in two-dimensional detectors in thermal infrared wavelengths enables us to take thermal images of the target asteroid at a glance. This is a new tool in planetary missions to measure the thermo-physical properties of the uppermost planetary surface, and we adopt this tool both for scientific and mission purposes on Hayabusa2.

C-type asteroids are primitive and the most abundant type of asteroids in the solar system that preserves a clue to understanding the origin and evolution of the solar system, since it is less evolved (less thermally altered) due to its smaller size compared to planets and large moons. A significant physical property that would be still preserved in most primitive asteroids is the physical condition, involving packing, porosity, and grain size distribution. In the planetary formation scenario, fine grains such as silicate dusts and ices in the proto-solar nebula were accreted to form small bodies called planetesimals, which should have been porous and loosely bound rubble-pile objects, several to tens of kilometers in diameter. Planetesimals were destructed into fragments and coalesced in impact events, and grew consequently to form larger bodies like planets. The interiors of the growing bodies were pressurized and compacted by meteor impact events and gravitational lithostatic force to become denser, less porous bodies. In the larger bodies, aqueous and thermal alteration processes should have occurred due to their volatile-rich composition and internal

heat sources by radioactive nuclides. However, smaller primitive bodies might have avoided the occurrence of such pressurized or altered processes and still remain in a relatively primordial condition. Icy components could have been possibly lost by sublimation to form very porous and fluffy textures. Indeed, asteroid 953 Mathilde, the only C-type asteroid ever explored by NASA's Near-Earth Asteroid Rendezvous Shoemaker mission, has a low density of $1300 \pm 300 \text{ kg m}^{-3}$ and on its surface, huge craters of hemispheric scale were found, which could be caused by meteor impacts into the loosely bound materials (Veverka et al. 1999).

The physical state of the surface is informed through thermal imaging, or thermography. Thermo-physical properties of the uppermost surface are characterized by grain size, porosity, or packing of the surface materials. But direct evidence of thermo-physical properties of primitive bodies is limited despite recent explorations. Thermal inertia values for Comet 9P/Tempel-1 and Comet 103P/Hartley-2, although still controversial, have been estimated to be 50 or 150, using the data of 3 to 5 μm near-infrared spectroscopy taken during flybys by NASA's Deep Impact and EPOXI missions (Groussin et al. 2013), respectively. These values are consistent with relatively fluffy, porous materials. During the historic landing of the Rosetta/ Philae lander, the surface of Comet 67P/ Churyumov-Gerasimenko was observed to be harder than predicted (Biele et al. 2015; Spohn et al. 2015).

A C-type asteroid is categorized by a flat, featureless reflectance spectrum in visible to near infrared wavelengths, and considered to be the origin of carbonaceous chondrite meteorites. But a carbonaceous chondrite meteorite found on the Earth should be the most consolidated part of the parent body and might not preserve its original physical condition because of break-up during the ejection from the parent body or during entry into the terrestrial atmosphere. In addition, the surface of C-type asteroids should have undergone some degree of processing such as (i) dehydration due to heating by the Sun; (ii) gardening by meteor impacts and ejecta sedimentation; (iii) space weathering through spattering by solar wind irradiation, dissociation by solar ultraviolet photons, or micro-cratering by micro-meteor impacts; and (iv) fracture by thermal fatigue from cyclic temperature changes caused by asteroid rotation. Thus we know something of C-chondrite meteorites but we know little about C-type asteroids without conducting detailed in situ observations and detailed analysis of returned samples.

The physical state of the surface, i.e. whether it is covered with fine soils, pebbles, or dense rocks, indicates its history of surface processes undergone in the past. Asteroids are typically less dense ($<1500 \text{ kg m}^{-3}$ for C-type, 2000 kg m^{-3} for S-type) than terrestrial rocks (2500 to 3300 kg m^{-3}), suggesting that the asteroid is very porous (Consolmagno et al. 2008). This may be caused by interstitial spaces between rocks or the existence of micro-porosity such as fine pores or cracks inside of rocks. Intense meteor impacts cause destruction of the asteroid body, followed by re-accretion of impact fragments to form smaller rubble-pile asteroids, occasionally with large boulders found on their surface, such as 25143 Itokawa (Fujiwara et al. 2006). Impact cratering produces ejecta sedimentation consisting of pebbles and finer grains, although most fine grains tend to be lost by ejection due to the low escape velocity. Impact cratering also causes shaking of the whole asteroid (asteroid quake) to trigger granular flow, resulting in the geological dichotomy with the existence of flat and rough terrains on the same asteroid like Itokawa (Yano et al. 2006). Dense rocks were formed inside the larger parent body by lithostatic pressure and thermal metamorphism, but they could be exposed on the asteroid surface by later fragmentation of the parent body by intense impact events.

The physical state of the surface can be derived from thermo-physical properties such as thermal inertia. Thermal inertia is defined as $(k\rho C_p)^{0.5}$ in the SI unit of $\text{TI} = \text{J m}^{-2} \text{K}^{-1} \text{s}^{-0.5}$,

Table 1 Relations of thermal inertia to surface physical state

| Thermal inertia: I [$\text{J}^{-2} \text{s}^{-0.5} \text{K}^{-1}$] | Surface physical state | Example |
|---|---|--------------------------------------|
| ~10 | Very fluffy, high porosity (~80 %) | Ceres, Martian soils |
| ~50 | Fine sand ($d < 100 \mu\text{m}$) | Lunar regolith |
| 100~200 | Sandy regolith ($d \sim \text{mm}$) | Eros soil |
| 200~400 | Pebbles ($d \sim \text{cm}$) | Itokawa flat terrain (Muses-C Regio) |
| 400~1000 | Boulders, rock fragments ($d < \text{m}$) | Itokawa rough terrain |
| 1000~2000 | Rocks with high porosity | |
| 2000~ | Monolithic rocks | |

where k is thermal conductivity of the material, ρ is its density, and C_p is its specific heat at constant pressure. For a material of compact density ρ_0 and porosity φ , the bulk density becomes $\rho = \rho_0(1 - \varphi)$. More fluffy or porous materials (low ρ) which tend to have a low value of k due to a small cross section for heat flow typically have lower thermal inertia. For lower thermal inertia, the surface on a rotating asteroid shows a sharper and larger increase and decrease of temperature at the dawn and the dusk areas, respectively. On the other hand, denser materials (high ρ) typically have higher thermal conductivity and have higher thermal inertia. In this case, the thermal energy sinks into the interior in the day time and is released from the interior during night time, so that the surface temperature shows fainter and weaker temperature variation with a delayed time of peak temperature. Thus, thermal inertia is the physical property that informs the surface conditions which can be measured from orbit. This is applicable to understanding and characterizing the surface scientifically, and also to constraining the rock distribution to avoid hazardous landing areas or examining the thermal environment for safe operation for spacecraft. A typical relation of thermal inertia to the surface physical state is shown in Table 1 (e.g., Delbo et al. 2007; Okada 2016).

We briefly describe thermal experiments to be conducted in the Hayabusa2 mission in Sect. 2, explain the objectives and requirements for the thermal infrared imager TIR in Sect. 3, show the instrumentation of TIR in Sect. 4, display some performance characteristics of TIR in Sect. 5, mention future observation plans during the cruise and asteroid rendezvous phases in Sect. 6, and summarize this paper in Sect. 7.

2 Thermal Experiments in Hayabusa2

2.1 Outline of Thermal Experiments on Hayabusa2

On Hayabusa2, thermal experiments investigating the surface of C-type asteroid Ryugu will be carried out by both remote sensing and in situ. TIR will conduct thermal emission imaging observations from the Home Position, about 20 km altitude sunwards from the asteroid surface almost every week during the 1.5-year-long asteroid rendezvous phase. TIR will continually take images of thermal emission of the whole asteroid surface in the 8 to 12 μm wavelength band every 512 seconds, during one asteroid rotation which is 7.63-hours long. In addition, when the spacecraft approaches the surface, TIR will also take thermal images from a lower altitude position, and spatially higher resolved images will consequently be taken. Using the TIR data, a global thermo-physical model of the asteroid will be constructed. The radiometer (MARA) (Grott et al. 2016) on the surface lander (MASCOT) (Ho

et al. 2016) deployed from Hayabusa2 will continuously measure the thermal emission off the surface at one location through day and night for two asteroid days. MARA data is complementary to that of TIR which observes mainly from the day side, and contributes to improving the thermo-physical model.

2.2 Summary of Hayabusa2 Mission

Hayabusa2 is the second asteroid explorer organized by the Japan Aerospace Exploration Agency (Tsuda et al. 2013; Tachibana et al. 2014; Okada 2014). It was successfully launched on 3 December 2014, and will rendezvous with near-Earth asteroid Ryugu in 2018 and perform a series of remote sensing, surface robot experiments, and impact experiments there, as well as collect a sample from the surface of the asteroid, then return the sample to Earth in 2020. Hayabusa2 has five remote-sensing experiments including an optical imager (ONC), laser ranging (LIDAR), near infrared spectrometer covering the 3 μm absorption band (NIRS3), thermal infrared imager (TIR), and radio science. Hayabusa2 also carries three small rovers MINERVA-II and a small lander MASCOT (Mobile Asteroid Surface Scout) developed in collaboration with European countries. MASCOT is a 10-kg sized hopping lander which has a wide angle imager (CAM), a 6-band thermal radiator (MARA), a 3-axis magnetometer (MAG), and a hyperspectral infrared microscope (MicrOmega). Hayabusa2 has a sampling device (SMP), and impact experiment devices including a small carry-on impactor (SCI) and a deployable camera (DCAM).

The science goals of Hayabusa2 aim to understand the origin and evolution of materials in the solar nebula and in the asteroid parent bodies, as well as to constrain the physical properties of small bodies during the planetary accretion processes. It is essential in Hayabusa2 to conduct global to local to micro-scale observations by exploiting the synergy of remote sensing, surface measurements, and analysis of returned samples.

2.3 Target Asteroid Ryugu

The target body to be visited by Hayabusa2 is 162173 Ryugu, and its characteristics are tabulated in Table 2 (e.g., Müller et al. 2011; Ishiguro et al. 2014). Ryugu is a C-type (C_g) near-Earth asteroid, and its perihelion and aphelion is 0.96 and 1.42 AU, respectively. The body has a roughly rounded shape with about 0.9 km in diameter, as derived from visible and infrared ground observations. The asteroid's period of rotation is 7.63 hours. Its reflectance spectrum is relatively featureless and flat, indicating a C-type asteroid in taxonomy. Although most previous observations have a low signal-to-noise ratio, one measurement appears to show a faint absorption at the 0.7 μm band (Vilas 2008), suggesting a CM chondrite-like material. Its averaged albedo is about 0.05, consistent with the typical C-type asteroid. Its current best estimate of global thermal inertia is 250 ± 50 (TI), indicating the surface is unlikely to be covered with lunar-like fine regolith or monolithic dense large boulders, but more consistent with pebbles. The only C-type asteroid explored to date is the relatively large and low-density asteroid 953 Mathilde, considered to be a very loosely bound rubble-pile object. To date, we do not know whether Ryugu resembles Mathilde or is completely different from this known asteroid.

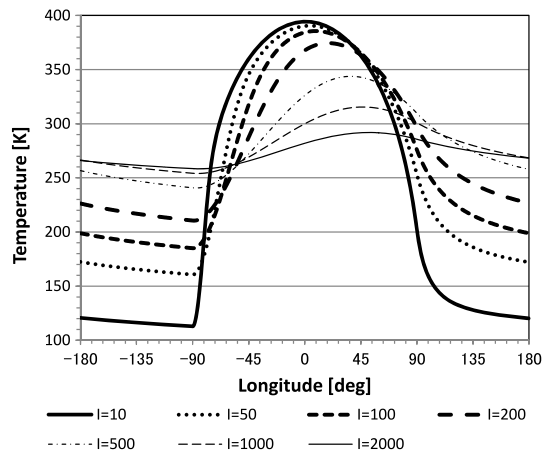
2.4 Temperature Profile on Asteroid Surface

The surface physical properties of the asteroid would indicate the history of surface processes undergone in the past, depending on whether the surface is covered with fine soils,

Table 2 Characteristics of 162173 Ryugu (e.g., Müller et al. 2011; Ishiguro et al. 2014)

| | |
|------------------------------------|---|
| Taxonomic type | C _g |
| Diameter | 0.87 ± 0.03 km |
| Axis ratio | $a/b = 1.0153$, $b/c = 1.0135$ |
| Rotation period | 7.63 ± 0.01 hour |
| Pole axis (λ , β) | $(329, -39) \pm 20^\circ$ |
| Geometric albedo (P _v) | 0.05 |
| H | 18.82 ± 0.021 |
| G | -0.110 ± 0.007 |
| Thermal inertia | $250 \pm 50 \text{ J m}^{-2} \text{ s}^{-0.5} \text{ K}^{-1}$ |
| Orbit (solar distance) | 0.9633–1.4159 AU |

Fig. 1 Calculated temperature profiles as a function of surface thermal inertia for the equatorial region of an asteroid with a rotational period of 7.63 hours, where albedo = 0.05, emissivity = 0.93. Details are given in the text



pebbles, porous boulders or dense rocks. Asteroids are typically less dense than terrestrial rocks, implying higher porosity.

Thermo-physical properties are highly affected by the physical state of the surface. Since the heat transfer through a porous or fluffy surface is small, the heat radiation from the Sun is deposited in the thin layer with low heat capacity at the uppermost surface and never penetrates to greater depths. In this case, the surface temperature increases sharply at dawn, but also decreases fast at dusk. On the other hand, heat transfer is larger in a denser, more conductive surface, and part of the heat input from the Sun sinks into the interior during daytime, but is released from there during nighttime. In this case, the temperature changes become rather moderate and the timing of peak temperature is delayed from the local noon.

Figure 1 shows an example of the temperature profile as a function of surface thermal inertia at the equatorial region of an asteroid with a rotational period of 7.63 hours, where the solar distance is 1 AU, the rotation pole is perpendicular to the asteroid orbital plane, and the surface albedo and emissivity are 0.05 and 0.93, respectively. For the very fluffy surface case (the thermal inertia $I = 10$ TI), the peak temperature is about 400 K almost at noon, while the temperature becomes 110 K in the nighttime. For the case of pebbles ($I = 200$ TI), the peak temperature is about 370 K in the afternoon at 18° longitude while the temperature is higher than 210 K even during nighttime. For the dense rock case ($I = 2000$ TI), the temperature ranges between 250 and 300 K and the peak temperature is approximately at 45° longitude.

Table 3 Targets and the possible objectives for TIR observations

| Target | Description | Operation |
|--------------------------------------|--|------------|
| Boulders | Evolution of materials originated from parent body interior | LA, CU, HP |
| Crater walls and interior | Direct probing of interior materials and structures | LA, HP |
| Regolith | Flow and sedimentary processes under micro gravity | HP, LA, CU |
| Overall thermo-physical properties | Comparison with ground observation | HP, LA |
| Yarkovsky/Yorp effects | Total mass, moment of inertia in asteroid | HP |
| Phase function (angular relation) | Updating TIR emission phase functions for roughness modeling | HP |
| Moons | Orbiting satellite for gravity measurement | HP |
| Dust clouds | Evidence of levitation, and existence of floating dust | HP |
| Asteroid shape model | Asteroid shape modeling including night time | HP |
| Geologic features | Detection of features such as ejecta, sediments, ponds, buried rocks | LA, HP |
| SCI crater search | Finding the SCI impact crater using temperature difference | LA, CU, TD |
| Touchdown (TD) site | Touchdown site selection and geologic context description | CU, TD |

Operation range: HP: Home position (10 ~ 20 km), LA: Low altitude (1 ~ 5 km), CU: Close-up (0.1 ~ 1 km), TD: Touch-down (<0.1 km)

We have conducted numerical studies with a thermal model of asteroid Ryugu as well as general cases for a variety of thermal inertias and pole inclinations in more detail, which will be reported in the companion paper (Takita et al. 2016).

3 Objectives and Requirements of TIR

3.1 Scientific Objectives of TIR

The main goals of TIR for the investigation of thermo-physical properties of the asteroid surface are (1) to understand the origin and evolution of asteroids and (2) to characterize the current state of a micro-gravitational small body. The targets and their possible objectives for TIR observations from various altitudes are shown in Table 3. In Fig. 2 we summarize the traceability map for the science objectives, observation targets, information requirements, and the performances required for TIR.

3.1.1 Understanding the Origin and Evolution of Asteroids

TIR will observe the asteroid structures found on the surface or inside the huge craters which are indicative of the asteroid formation processes. A homogeneously porous structure is likely in the event that the asteroid was formed by simple accretion growth of silicate dust and ice compounds, followed by sublimation of volatile components. On the other hand, a homogeneously dense structure is considered if the asteroid (or its parent body) has

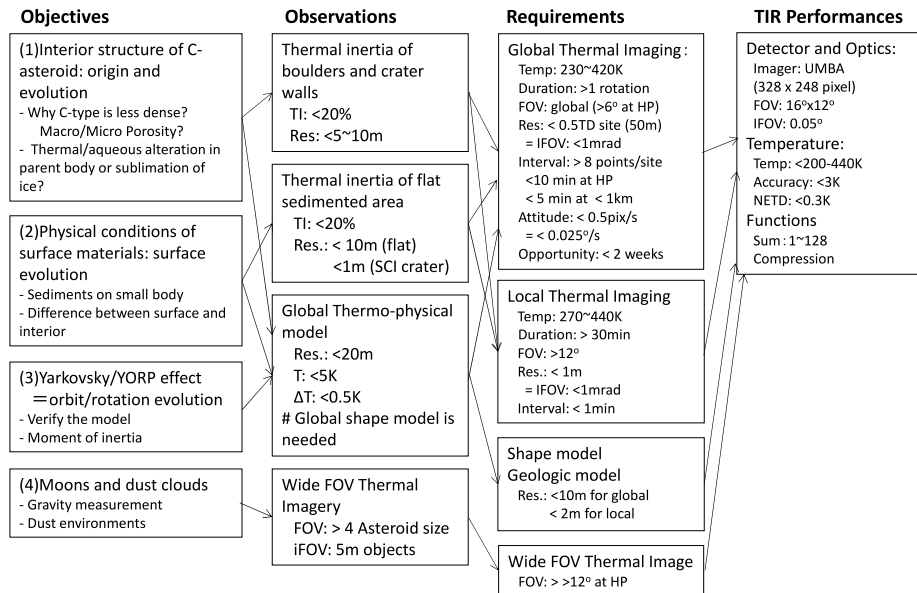


Fig. 2 Traceability map for science objectives, observations, information requirements, and TIR performance requirements

undergone a severe compaction process by impacts and thermal alteration after the body was accreted. Very heterogeneous features are expected if the asteroid is a rubble-pile object and composed of multiple boulders of various sizes that originated from impact fragments of an evolved parent body.

A thermal inertia map that shows the regional distribution of surface physical properties such as porosity or grain size lets us constrain the asteroid history. The thermal inertia of huge boulders implies a degree of past compression in the parent body. The thermal inertia of smooth flat area can deliver important information on the formation by ejecta sedimentation or granular flow under micro-gravity. The composition of surface materials cannot be determined solely by TIR but could be much improved if the thermal emission component estimated from TIR data is used for subtraction from the NIRS3 spectrum (Iwata et al. 2016).

3.1.2 Characterizing the Current State of Micro-Gravitational Small Body

The orbital and rotational evolution of solar system objects is affected by two thermal effects, the Yarkovsky effect and the YORP (Yarkovsky-O'Keefe-Radzievskii-Paddack) effect (e.g., Bottke et al. 2006). If an accurate thermo-physical model is constructed, the asteroid's density or moment of inertia is constrained. The relation of asteroid size to thermal inertia or typical thermal conductivity can be compiled from ground-based observations (Delbo et al. 2007). TIR will provide a disc-resolved thermal inertia map of Ryugu, which will be a good *ground truth* to verify and improve the thermal models of the asteroid. Thermal imagery can be a more powerful tool for detecting geologic features than optical imagery can, which is especially true for surfaces with varying porosity, such as crater ejecta, veins, grooves, or buried structures. Thermal emission from the dust surrounding the asteroid which might be

supplied by electrostatic forces (levitation) or micro-meteor impacts might be detected by thermal imagery.

3.2 Mission Objectives of TIR

TIR data is also used for mission objectives such as landing site selection as well as safe descent operation for sample collection. In Fig. 3, we present the traceability map for mission objectives, observation targets, requirements for information, and the performance required for TIR, focused on conducting the descent and touchdown operations.

3.2.1 Landing Site Selection

Thermal inertia derived from TIR observations reflects the typical particle size of the regolith layer so that the landing site can be selected that is most suitable for sample collection from the viewpoint of particle size (1 mm diameter), even from Hayabusa2's Home Position. If particles are 1 mm in size, the sample is expected to contain most of the significant minerals and textures so that it is sufficiently informative for analysis. If particle size is less than 0.1 mm, as was typical in the case of samples returned by Hayabusa, the sample may only include a limited subset of minerals and textures (Tachibana et al. 2014). On the other hand, the sampling device should collect samples much smaller than 10 mm, so that the best size range for sample collection is about 1 mm in diameter. The thermal inertia map produced by TIR will help finding the best area with regard to grain size.

Using the thermal inertia map by TIR, the highest temperature ever experienced in the asteroid's history is estimated at a given depth for each site on the asteroid, according to a dynamically simulated trajectory of the entire lifetime of a near-Earth asteroid (Michel and Delbo 2010). This may be important for determining what kinds of organic matter are lost due to thermal processing or still remain on the surface of the asteroid, and may be one of the key pieces of information for landing site selection.

3.2.2 Safe Operation for Descent of Spacecraft to the Surface

The thermal emission energy of the surface of the asteroid as well as the surface temperature are measured by TIR, and also estimated at any given time using the thermo-physical model constructed by TIR observations. Thermal inertia maps are often used to estimate rock or boulder populations (Golombek et al. 2003). Prior to the descent and touchdown operation, it is important to assess whether the surface thermal environment and boulder distribution is hazardous for landing or not.

3.3 Requirements for TIR Observation and Specification

The desired performance of TIR is discussed in 2 and 3 for science and mission objectives, respectively. The spatial resolution expected during typical operation phases is shown in Table 4, where IFOV = 1 mrad. Spatial resolution is subject to the following three requirements: (1) TD candidate site (flat area of >50 m) must be resolved by at least 2 pixels from HP ($H = 20$ km), which is <1.2 mrad or 0.07° ; (2) SCI crater ($D > 2$ m) must be resolved by at least 2 pixels from the low altitude ($H = 1$ km), which is <1 mrad or 0.057° . The touchdown position touched by sampler horn ($D = 20$ cm) must be resolved by at least two pixels from 50 m altitude, which is <2 mrad or 0.11° . In summary, IFOV of TIR should be <1 mrad. We summarize the requirements for TIR observation and specification in Table 5.

Table 4 Estimated spatial resolution for main operation phases of TIR assuming an IFOV of approx. 0.88 mrad

| Observation phase | Altitude [km] | Spatial res. [m] | Remarks |
|------------------------------------|---------------|------------------|--|
| AP: Before arrival | 2000~20 | 1700~17 | <ul style="list-style-type: none"> • Asteroid light-curve measurements, compared with ground observations • Search for moons, observation of dust environments |
| HP: Global features | 20~10 | 17~9 | <ul style="list-style-type: none"> • Image every several minutes for one rotation, once a week • Solar phase angle 0–45°, solar distance 0.96–1.42 AU |
| Mid-altitude: Global and high res. | ~5 | ~4 | <ul style="list-style-type: none"> • Several times, global coverage and higher resolution • Every several minutes in one rotation |
| Low-altitude: Local site features | ~1 | ~1 | <ul style="list-style-type: none"> • 1 h observation before TD, Landers/SCI deployment • 280 m × 210 m area, SCI crater finding |
| TD: Local site, high res. | <0.05 | <0.05 | <ul style="list-style-type: none"> • Several time for TD and TD rehearsals • Highest resolution for each sites |
| XO: Larger phase angle | 20~10 | 17~9 | <ul style="list-style-type: none"> • Large phase angle observation ($\theta_s > 45^\circ$) • From East–West, North–South |

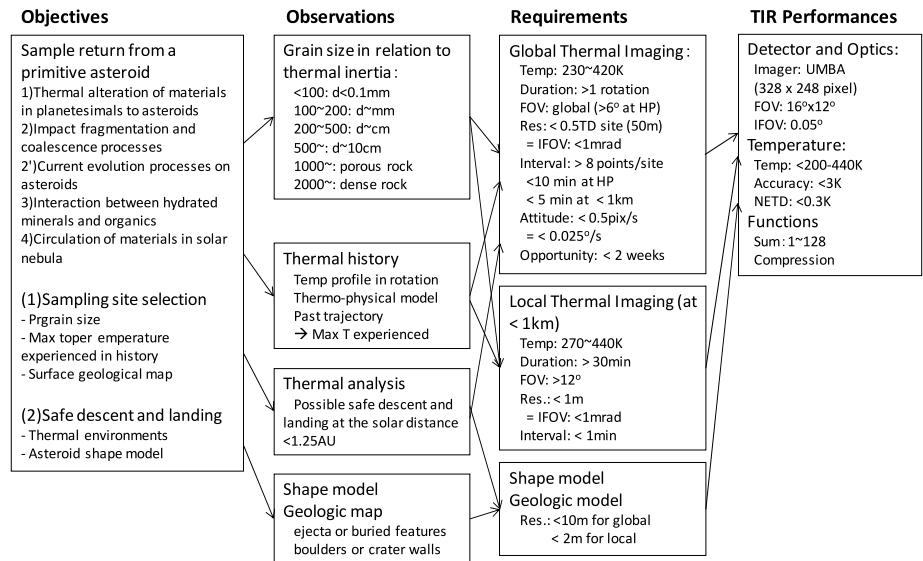


Fig. 3 Traceability map for mission objectives, observations, information requirements and TIR performance requirements, focused on conducting the descent and touchdown operations

Table 5 Requirements for TIR observations and specifications for each objective

| Objectives | Requirements for TIR observation | Requirements for TIR specification |
|--|--|--|
| <p>Thermo-physical properties of Boulder (originates from parent body interior)</p> <ul style="list-style-type: none"> • density of C-type asteroid is low • thermal alteration in parent body • similarity to C-chondrites | <p>Thermography of boulders</p> <ul style="list-style-type: none"> • T profile by rotation (accuracy <5 K) • different solar distance • spatial resolution <10 m | <p>FOV: >6° @HP, >10° @1 km IFOV: <1 mrad @HP, 1 km NETD: <0.5 K @350 K ΔT: <5 K @350 K</p> |
| <p>Thermal inertia distribution of Crater interior (current interior structure)</p> <ul style="list-style-type: none"> • Interior density structure of 1999JU3 • Interior heterogeneity of 1999JU3 | <ul style="list-style-type: none"> • T profile by rotation (accuracy <5 K) • different solar distance • spatial resolution <10 m | <p>FOV: >3° @HP, >10° @1 km IFOV: <1 mrad @HP NETD: <0.5 K @350 K ΔT: <5 K @350 K</p> |
| <p>Thermal inertia map on regolith surface</p> <ul style="list-style-type: none"> • grain size distribution and formation of surface sedimentation • regolith sticking or cohesion mechanism (for very fluffy case) • thermal conduction under microgravity | <p>Global thermal mapping:</p> <ul style="list-style-type: none"> • T profile by rotation (accuracy <5 K) • different solar distance • spatial resolution <20 m <p>Global shape model (<10 m res.) Surface conditions informed by ONC, MINERVA, MASCOT, sample</p> | <p>FOV: >6° @HP IFOV: <2 mrad @HP NETD: <0.5 K @350 K ΔT: <5 K @350 K Shape model: 10 m res. Surface condition and materials (grain size, porosity, composition)</p> |
| <p>Comparison with ground-based asteroid thermal model</p> <ul style="list-style-type: none"> • heterogeneity from surface to interior (formation process of 1999JU3) • consistency with ground based TPM • Verification of diameter-TI relation by Delbo et al. (2007) | N.A. | N.A. |
| <p>Yarkovsky/YORP effects</p> <ul style="list-style-type: none"> • Relation and comparison with thermal emission un-isotropy to evolution of orbit and rotation • Asteroid mass, moment of inertia | <p>Global thermal mapping:</p> <ul style="list-style-type: none"> • T profile by rotation (accuracy <5 K) • different solar distance • spatial resolution <20 m <p>Global shape model (<10 m res.) Rotation change (~°/year), Orbit change (range <km)</p> | <p>FOV: >6° @HP IFOV: <2 mrad @HP NETD: <0.5 K @350 K ΔT: <5 K @350 K Shape model: 10 m res. Rotation detected by ONC (<1°) Range (< a few km)</p> |
| <p>Uppermost surface fine grains</p> <ul style="list-style-type: none"> • Existence and origin of fine grain layer | <p>Temperature distribution on boulder or base rock</p> <ul style="list-style-type: none"> • T difference between fresh surface on crater center to the surrounding area with spatial res. <1 m. | <p>FOV: >6° @1 km IFOV: <1 mrad NETD: <0.5 K @350 K ΔT: <5 K @350 K</p> |

Table 5 (Continued)

| Objectives | Requirements for TIR observation | Requirements for TIR specification |
|--|--|--|
| Thermal modeling: topographic and roughness effects <ul style="list-style-type: none"> • self-heating effects • solar phase angle effect by grain size | Global thermal mapping and local site high res. thermal imaging <ul style="list-style-type: none"> • T profile by rotation (<5 K) • Data at different solar distance • Spatial res.: <1 m Global shape model (<10 m res.) Local surface model (<10 cm res.) Surface conditions informed by ONC, MINERVA, MASCOT, sample | FOV: >6° @1 km IFOV: <1 mrad NETD: <0.5 K @350 K ΔT: <5 K @350 K Shape model: 10 m res. Surface condition and materials (grain size, porosity, composition) |
| SCI impact crater observation <ul style="list-style-type: none"> • Difference from surface to interior • Area and grain size of ejecta | Local high res. Thermal imaging <ul style="list-style-type: none"> • Inside and surrounding area of the SCI crater • T profile by rotation (<5 K) | FOV: >6° @ <1 km IFOV: <1 mrad NETD: <0.5 K @350 K ΔT: <5 K @350 K |
| Surface geology and shape modeling (even in the night side) for $I > 50$. <ul style="list-style-type: none"> • Contemporary to optical shape model | <ul style="list-style-type: none"> • Global thermal mapping: • T profile by rotation (<5 K) • Multiple solar distance • Spatial res.: <20 m | FOV: >6° @HP IFOV: <1 mrad NETD: <0.5 K @350 K ΔT: <5 K @350 K |
| Dust measurement <ul style="list-style-type: none"> • Dust environments around asteroid • Dust ejection by SCI impact | <ul style="list-style-type: none"> • Wide angle (> a few asteroid diameter) • Long time exposure in total (several seconds) | FOV: >12° Total integration: >5 s |
| Search for moons <ul style="list-style-type: none"> • Existence of moons around small body • Gravity information | <ul style="list-style-type: none"> • Wide angle (> a few asteroid diameter) • Size down to 10 m class (1/100 (mass: 10^{-6})) | FOV: >12° @HP (20 km) IFOV: <1 mrad NETD: <0.5 K @350 K ΔT: <5 K @350 K |

4 Description of the Thermal Infrared Imager TIR instrument

4.1 Outline of TIR

TIR is a single-band thermal infrared imager with the wavelength ranging from 8 to 12 μm and the field of view covering $16 \times 12^\circ$. The detector is based on a two-dimensional uncooled micro bolometer array (NEC 320A) with 328×248 effective pixels, a germanium detection window of anti-reflection coating, and a thermoelectric cooler module (Peltier module) to control the detector temperature at 313 K (40°C) within 0.1 K stability. The spatial resolution is about 0.05° per pixel, which corresponds to 17 m per pixel when observing the asteroid from the Home Position at 20 km altitude. TIR has a shutter mechanism driven by a stepping motor and two positioning sensors. Images are taken in pairs, with the shutter closed and open respectively, and each pair of images thus consists of one dark image (shutter closed) and one exposed image (shutter open). The thermal images are then derived from the subtraction of the two images. The shutter temperature is monitored with 0.01 K accuracy, so that the bias of each pixel is cancelled. The imager has been well calibrated in the laboratory from 233 K to 423 K, which covers the expected temperature range of the sunlit surface of asteroid Ryugu. The detectable temperature range is wider than this, from

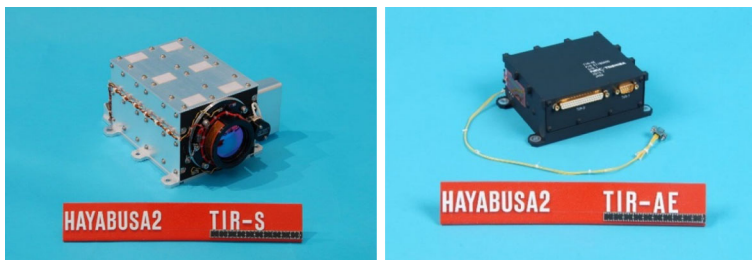


Fig. 4 Photographs of TIR-S (*left*) and TIR-AE (*right*)

Table 6 Performance of TIR

| | |
|----------------------------|---|
| Mass | 3.28 kg |
| Power | 18 W (nominal) |
| Detector | Uncooled bolometer array NEC 320A (anti-reflection coating) |
| Pixels | 344 × 260 (effective 328 × 248) |
| Field of view (FOV) | 16.7 × 12.7° |
| IFOV | 0.89 mrad (0.051°) |
| MTF (@Nyquist Freq.) | 0.5 |
| F-number | 1.4 |
| Temperature range | 233–423 K (well calibrated), 150–460 K (detectable range) |
| NETD | <0.3 |
| Absolute temperature range | <3 K |
| A/D converter | 12 bit (15 bit after summed) |
| Reference temperature | Shutter temperature (monitored) |
| Frame rate | 1/60–2.1 s (summation for $m = 1$ to 128 images) |

150 K to 460 K, which covers the whole asteroid even in the nighttime for the thermal inertia >50 TI.

4.2 Configuration and Functions of TIR

TIR is a light-weighted thermal infrared imager, inherited from the Longwave Infrared Camera (LIR) onboard Akatsuki (PLANET-C) Venus climate orbiter (Fukuhara et al. 2011), which enabled development on a very short timescale and use of the same apparatus for calibration for the cold temperature range in the space chamber. TIR consists of the sensor unit (TIR-S), the power supply unit (TIR-AE), and the digital electronics unit (DE) (Hihara et al. 2014). The photographs of TIR-S and TIR-AE are shown in Fig. 4, and the performance of TIR is shown in Table 6. A 3D image of TIR-S is shown in Fig. 5.

TIR-S consists of two parts: the sensor body and the hood (sunshade). The sensor body includes the optics, detector, analog electronics, analog-to-digital converter, image processor, data interface to DE, telemetry and command interface, Peltier cooler controller, and power regulation units.

The optics unit has three pieces of Germanium lens, the mechanical shutter, and a band pass filter attached in the aperture. The diameters of lens and aperture are 47 mm and 25 mm, respectively, and the F value is 1.4. The filter passes from 8 to 12 μm . The mechanical shutter is located between the lens and filter, and operated using a stepping motor. The

Fig. 5 The characteristic of TIR-S (modified from Fukuhara et al. 2011)

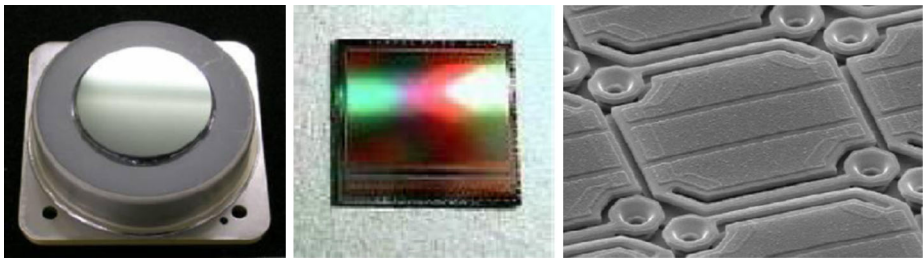
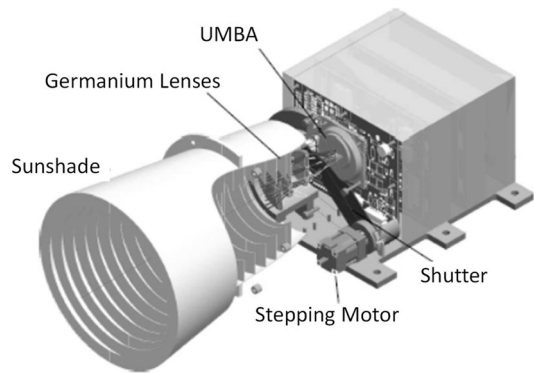


Fig. 6 Photograph of the detector package and the uncooled micro-bolometer array in the package, and scanning electron microscope image of a detector pixel (from Hihara et al. 2014)

shutter is only opened to take images and basically closed to protect direct irradiation of sunlight for contingency. The shutter is made of an aluminum plate with almite processing, or anodic oxidized coating, and its hemispherical emissivity is 0.89. The temperature of the shutter is monitored at 0.01 K accuracy as Shutter Temperature, which is used as the reference temperature for calibration. The shutter position, i.e. whether it is open or closed, is detected with two position sensors. The filter is attached in the aperture, whose temperature is monitored at 0.01 K accuracy as Case Temperature. The optics unit is thermally controlled by the Heater Control Electronics (HCE) of the Hayabusa2 spacecraft. The temperature is monitored at 0.5 K accuracy with a sensor (Pt2000 resistance) as Channel 60A of HCE, and actually controlled in space within 0.3 K stability (monitored at 0.01 K accuracy as Lens Temperature in TIR-S), with proper settings of heater duty ratio and set points.

The detector unit NEC320A is originally a commercial package which includes the two-dimensional bolometer array of 344×260 pixels and the temperature control system using a Peltier cooler. The detector has 328×248 effective pixels. Each pixel has $37 \times 37 \mu\text{m}$ pitch and is 70 % of the detection area. Six pixels at the top and bottom in the vertical axis are used as optical black pixels. Eight pixels at the left in the horizontal axis denote no output (noise level) and the next 8 pixels are used as optical black pixels. The cooler unit keeps the detector temperature at 313 K (40°C) or 283 K (10°C), selected by commands, and controls it within 0.01 K stability. Temperature stability is critical to TIR's output, and the main reason for TIR operating at 313 K (40°C) is its higher sensitivity at this temperature. The temperature of the detector package is also monitored at 0.01 K accuracy as Package Temperature. The detector unit and a close-up of a detector pixel are shown in Fig. 6.

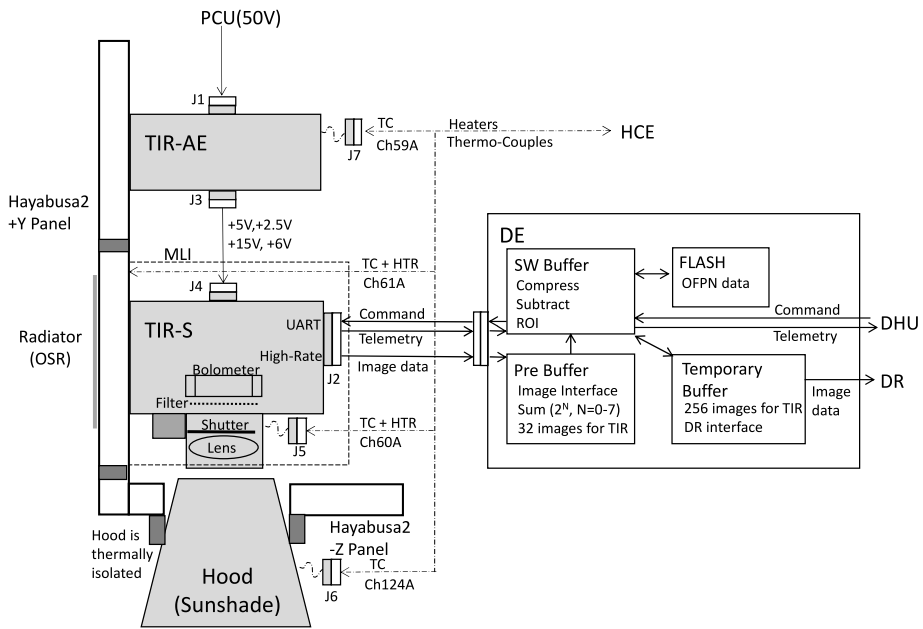


Fig. 7 Characteristic diagram of TIR-S, TIR-AE and DE interface

The hood is an aluminum-made horn-shaped sunshade to avoid direct input of sunlight. The length outside of $-Z$ panel is 150 mm, with a 122-mm diameter at the top. FOV of the hood is 22.92° and the avoidance angle is 52° . The outside of the hood is effectively a radiator using 0.2 mm thick Ag/Teflon without ITO (Indium Tin Oxide) coating. Inside the hood there is a baffle structure with anodic oxidation coatings on aluminum. The hood is mainly used to prevent sunlight from warming the optics, but direct sunlight can cause damage to the bolometer pixels. The hood is thermally isolated from the $-Z$ panel of spacecraft. Temperature is monitored by HCE as Channel 124A.

TIR-AE is the power supply unit that converts the unregulated 50 V bus power to +2.5 V and +5 V for data processing, +5 V for the detector, +6 V for the Peltier cooler, and +15 V for analog electronics. The temperature of TIR-AE is also monitored by HCE as Channel 59A.

DE is the digital electronics for DHU interface of all the scientific instruments and for the data recorder (DR). In addition, TIR uses the functions of DE such as the image data interface, image processing, image buffers (SDRAM 256 MB), and high-speed image data transfer to DR.

The characteristic diagram of the TIR and DE interface is shown in Fig. 7, and the diagram of signal flows and power lines in TIR-S and TIR-AE is shown in Fig. 8. Functions of each unit in TIR-S are summarized in Table 7, and details of functions related to TIR and related systems are shown in Table 8.

4.3 Imaging Processes of TIR

TIR has six operation modes including Off, Standby, Protect, Idling, Parameter Setting, and Imaging modes. TIR can take an image only during the Idling mode. After the unregulated

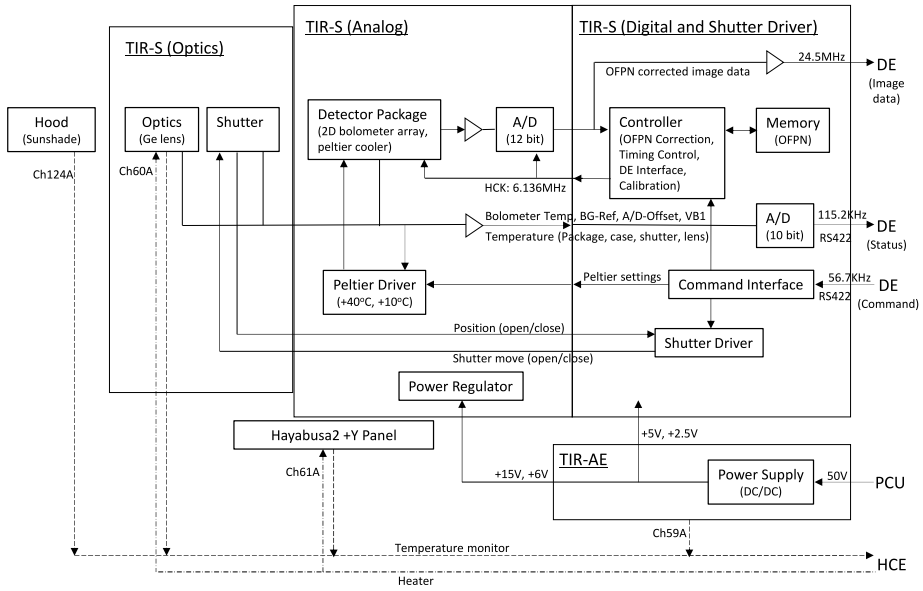


Fig. 8 Schematic diagram of signal and data flow, power lines, and temperature control lines in TIR-S and TIR-AE

Table 7 Summary of functions of each unit in TIR-S

| Unit | Functions |
|---------------------|---|
| Optics | <ul style="list-style-type: none"> Configuration: Germanium lens (3 pieces): $\phi 47$, $F1.4/FL = 42.2$ mm, $MTF > 0.5$ Concentrate IR lights from outside to focus on the detector Band pass filter to limit the wavelength of 8–12 μm |
| Shutter | <ul style="list-style-type: none"> Configuration: Stepping motor, shutter plate with positioning sensors, shutter controller Change the target: Incident lights and homogeneous target plate with Temp monitor |
| Detector package | <ul style="list-style-type: none"> Detector: detect the incident IR light that passes the filter and convert it to electronic signal Peltier cooler: stabilize the detector temperature at 313 K (40 °C) |
| Analog electronics | <ul style="list-style-type: none"> Amplifier for readout signal from detector unit and Analog-to-digital converter Controller for Peltier cooler in the Detector package Monitor the temperature of PCD and reference voltage in Detector package |
| Digital electronics | <ul style="list-style-type: none"> I/O Interface of command and telemetry to DE Timing clock generation for operation of detector Perform the internal calibration in Detector package Store the OFPN data into RAM Transfer of image data to DE after digitized by ADC |
| HK and telemetry | <ul style="list-style-type: none"> Detect the temperature at each unit and generate telemetry data Monitor the base temperature by Pt resistance sensor Multiplexer and analog-to-digital converter for all the HK data |

Table 8 Functions of TIR

| Functions | Contents | Remarks |
|---|---|---|
| Command response from DE | Control and parameter settings for TIR by commands. Maximum rate is 1/16 s (62.5 ms) | UART interface |
| Send telemetry to DE | HK data and command response after commanded. Every 1 second, and just before taking images | UART interface |
| Imaging | Take images at 60 frames/sec, and A/D conversion | |
| Image processing | Calibration of images with the OFPN data and the parameters set by commands | |
| Send images to DE | Send the numbers of images set by commands | Dedicated line |
| OPFN data readout and set | Read the OFPN data from DE flash memory and set into TIR-S memory | |
| Get HK telemetry | Get the latest HK data of TIR constantly and store them into the register | |
| Bolometer temperature control | Control the bolometer temperature at 40°C or 10°C by commands | Accuracy < ±0.1 K |
| Shutter open/close | Dark image and Reference temperature. Fine/course movement | Duration for 1 s |
| Onboard calibration | Calibration onboard for bolometer outputs duration | Duration for 40 s |
| Bolometer protection | Transfer to safe mode when the alert is detected | |
| Sunshade | Shield the direct sunshine or thermal emission off the asteroid to avoid the lens too heated | Avoidance angle of the sunshade is ±26° |
| Regulation of input current (DC/DC converter) | Regulate unregulated 50 V from PCU and supply +5 V(D), +5 V(A), +2.5 V, +6 V, +15 V | |
| Reference temperature | Monitor temperatures at Package, Case, Shutter, Lens, and Hood | Accuracy < ±0.1 K |
| Image summation | Sum the preset numbers of images at Pre-buffer of DE, by 2^M ($M = 0-7$), stored as 32 bit data. Stored address can be set for each image (max. 32 for TIR) | DE function |
| Image subtraction | Subtract between images stored in the buffer. Thermal image is derived by shutter-open image minus shutter-close one | DE function |
| Image summation by SW | Add, Subtract, multiply, divide images in the buffer. MEAN images for $N = 3-16$ images | DE function |
| Image compression | Compress images with StarPixel (lossless, lossy). ROI (region of interest) can be set. | DE function |
| Temperature control at lens | Lens temperature can be controlled by 0.5 K step by HCE | HCE function |
| Temperature control at TIR-S mounted panel | Panel temperature can be controlled by 0.5 K step by HCE | HCE function |
| Monitor temperature | Monitor the temperature of Sunshade (Hood) | HCE function |

Table 9 TIR operation mode

| Modes | Contents |
|-------------------|--|
| TIR Off | Power off |
| Standby | Initial state (peltier control = off) |
| Protect | Safe mode for detector (peltier control = on) |
| Idling | Ready for imaging |
| Parameter setting | Detector internal correction and calibration setting |
| Imaging | Image taking and Data output from TIR |

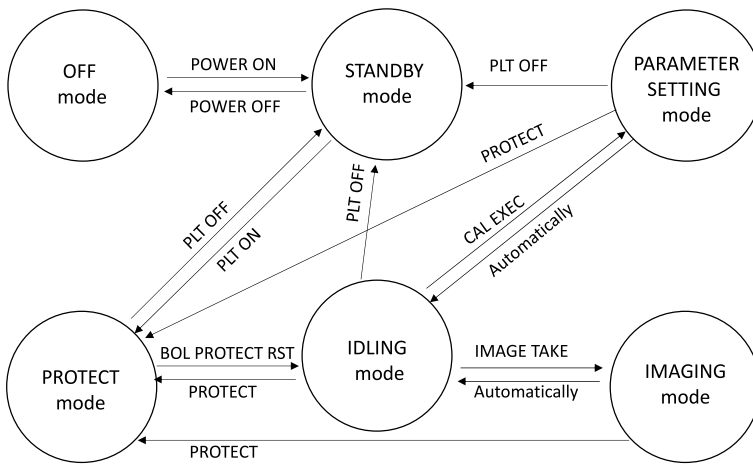


Fig. 9 Diagram of TIR mode transfer

50 V power is supplied from PCU to TIR-AE, TIR starts and enters Standby mode. The Peltier cooler must be activated by sending the PLT ON command, and TIR enters Protect mode after the temperature of the bolometer is controlled at 313 K (40°C). Then TIR moves to Idling mode by sending BOL PROTECT RST command. The onboard flat noise pattern must be set in the TIR memory before taking an image. One method is to conduct onboard calibration by CAL EXEC command. Another method is to upload the OFPN data from DE, which is constructed on ground and uploaded beforehand. The TIR image is taken by sending IMAGE TAKE command. After the image has been taken, TIR automatically moves to Idling mode again. The definition of each mode is shown in Table 9, while the mode transfer-by-commands are shown in Fig. 9.

The signal readout values from the two-dimensional bolometer array have a large diversity pixel to pixel. Therefore TIR always takes a pair of images when the shutter is closed and open as mentioned in Sect. 4.1, corresponding to a dark frame image and an exposed one, respectively, and then subtracts the dark frame image from the exposed one. The shutter is basically closed during the mission, so that the first image is usually taken when the shutter is closed. The shutter has the quasi black body surface colored black by anodic oxidation coatings with an emissivity ~0.89. Its temperature is kept at 300 K to 303 K and monitored at the resolution of 0.01 K. Thus the closed image can be used as the reference temperature for data analysis. The image is stored in the pre-buffer in the 1 MB area of image interface

in DE. The shutter is opened by the stepping motor in 1 second. Then the second image is taken when the shutter is open. The image is stored in the next 1 MB area of the pre-buffer. There are two buffers with 128 MB SDRAM, and up to 128 pairs of TIR images can be taken and stored in the pre-buffer, but 32 images (16 pairs) are the maximum allocation for TIR and the rest are used for ONC in the current plan.

After taking images, the analog electronics unit reads the output signals from the detector at 60 frames per second and digitizes them into 12 bit image data through the analog-to-digital converter. The readout data is compared with the onboard flat pattern noise (OFFPN) for each pixel and produced as image data in the image processor in DE.

4.4 Onboard Data Processing for TIR in DE

The readout image data is transferred to the pre-buffer in the image data interface of DE. Before taking the image, the number of images to be summed can be set by commands. Currently 2^N images are summed there, where $N = 0, 1, 2, \text{ to } 7$. The original image digitized in TIR-S is 12-bit data but treated as 16-bit data in DE. In case of $N > 4$, the image product becomes larger than 16 bit, so that the DE treats the TIR summed image as 32-bit data in the pre-buffer. The readout time, in case of $N = 6$ (64 images to be summed), will take $64 \text{ images} \times 1/60 \text{ second per frame} = 64/60 = 1.07 \text{ second}$ for the summed image. The time delay between the images with closed and open shutter is typically 2 seconds.

After the image sequence finishes, DE transfers the summed images stored in the pre-buffer to the software buffer, and then transfers them to the temporary buffer. Here only 16 bit data can be treated in the DE software buffer. The data compression algorithm used here is StartPixel (Hihara et al. 2014). The algorithm can only treat the image with 15-bit and 128×128 pixels. Thus, during this process, the images of 344×260 pixels \times 32-bit data in the pre-buffer are transformed to images of 384×256 pixels \times 15 bit, with 6 tiles of 128×128 pixels, and stored into the temporary buffer. In this procedure, four pixels at the bottom of the original image are erased, 40 pixels at the left are attached to the right, and all the data is bit-shifted to become 15-bit data as non-negative values in signed short format.

The pairs of images with shutter closed and open stored in the temporary buffer are subtracted to produce subtracted images. This operation is the equivalent of dark frame subtraction in conventional photometry. The subtracted images show good accuracy and stability is maintained quite well even if the temperature condition of TIR-S is changed. The subtracted images will be transferred to the data recorder (DR). Typically the image data is compressed using the StarPixel algorithm before transferring to DR.

Figure 10 shows examples of a TIR image pair of a 373 K blackbody target using the collimator (METS L-10-2.9, CI Systems) taken on 13 November 2013, and another TIR image pair of the deep sky in-flight observation taken on 27 February 2015. Image A is the shutter-open (exposed) image of the 373 K blackbody target and looks very noisy with dispersive bias pixel to pixel. Image B is the shutter-closed (dark frame) image, and Image C is derived by subtracting the two images, showing a clear blackbody target. The images D and E are a deep sky image (shutter open) and the corresponding dark frame image (shutter closed), respectively, while the image F is the result of subtraction of images D and E.

4.5 Observation Program

In the Hayabusa2 mission, scientific operations are nominally conducted using an automatic program called Observation Program (OP, hereafter). An OP consists of the software se-

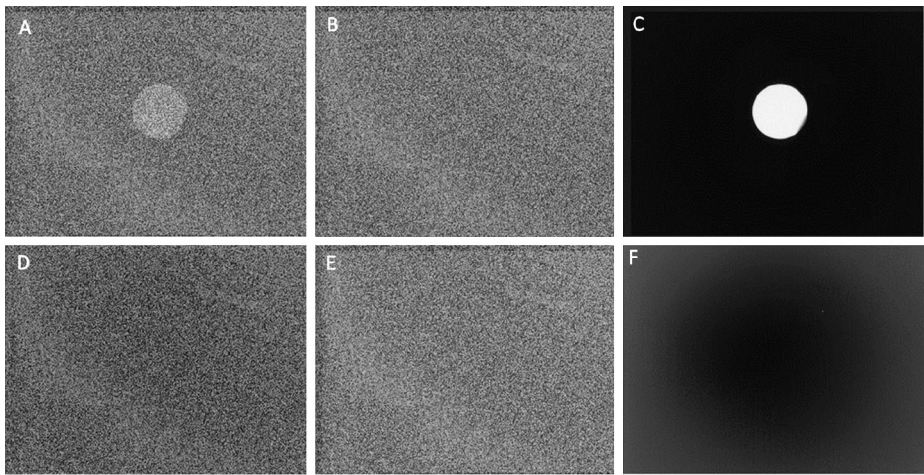


Fig. 10 Examples of TIR images are shown. Images of 373 K blackbody target using a collimator in front of TIR were taken in a pre-flight laboratory test on 13 November 2013 with shutter-open image (A), shutter-closed image (B), and the subtracted image (C). The deep sky images were taken on 27 February during the in-flight TIR with shutter-open image (D), shutter-closed (E), and the subtracted image (F). The readout values have large diverse biases pixel to pixel, but subtraction of the shutter-closed from the shutter-open images results in low-noise thermal images. In image F, TIR imaged the deep sky with an edge effect, and this is close to the background level of TIR

quences stored in DE, and 31 sequences can be stored at maximum. The sequences can be replaced by uploading new ones from the ground station. We have constructed and tested 17 OPs for TIR on the ground (see Table 10). At launch, only part of this program is stored in the DE because 31 OPs should be shared with all the instruments on Hayabusa2. The set of OPs should be changed before a new operation phase starts.

TIR-0×01 is the setup sequence which is used every time TIR turns on. TIR-0×02 conducts onboard calibration and take 4 images, which was mainly used for the system tests. This was also used for the first functionality test just after launch. TIR-0×03 to 0×05 are for the function, performance, and health checks. TIR-06 to 08 take 128 summed images suitable for the observations at Home Position or during the cruise phase. TIR-0×09 to 0×0C take 32 summed images and are more suitable for the observations at lower altitude from the asteroid, since a 32-summed image takes 0.5 seconds per image, while it takes 2.1 seconds for a 128-summed image. TIR-0×0B is the special OP to track the SCI (Small Carry-on Impactor) continuously in a 2-second interval (30 images) after its separation. TIR-0×0D, shutter closed, is used for checking the shutter movement. TIR-0×0E- 0F are 128- and 32-summed images for four thermal images, but 1 of them is a full image and 3 of them are only the equatorial region to reduce the amount of data. TIR-0×10 is the shutoff sequence of TIR to be used via OP. TIR-0×11 is the sequence of 4 times TIR-0×0E at a 512-second interval to be used during the descent phase of the Hayabusa2 spacecraft. In Table 10, the TIR OPs are shown with their functions, duration, designated partitions of DR, and the amount of data production for each DR partition. The DR partition 69 is mainly used for subtracted images, 6A is used for shutter-closed images, and 6F is for the mean of subtracted images for quick downlink if required.

Table 10 TIR operation program

| # | Name of Obs program | Function | Duration [sec] | DR Pt. | Data [MB] |
|----------|-------------------------------|---|----------------|----------------|-------------------|
| TIR-0×01 | Setup and OFPN loading | Peltier ON, Protect reset, parameter settings, OFPN data loading to TIR | 500 | NA | NA |
| TIR-0×02 | Cal-Check | Auto CAL without OFPN, $M = 64$ image × 4 set (C, S, A) Image Compression | 128 | 69 6A 6F | 0.4 0.8 0.1 |
| TIR-0×03 | Check1 (Function check) | $M = 64$ image × 1 set (C, S) Compressed | 64 | 69 6A | 0.2 0.4 |
| TIR-0×04 | Check2 (Performance check) | $M = 1, 16, 32, 64,$ 128×4 set (C, S, A) Image compression | 360 | 69 6A 6F | 2.0 4.0 0.5 |
| TIR-0×05 | Check3 (Health check) | $M = 1, 128 \times 16$ set (C, S, A) Image compression | 600 | 69 6A 6F | 3.2 6.4 0.5 |
| TIR-0×06 | Take1 (Nominal exposure) | $M = 128/N = 4 \times 1$ set (C, S) Image compression | 64 | 69 6A | 0.1 0.2 |
| TIR-0×07 | Take2 (Long exposure) | $M = 128 \times 16$ set (C, S, A) Image compression | 352 | 69 6A 6F | 1.6 3.2 0.1 |
| TIR-0×08 | Take3 (Short exposure) | $M = 128 \times 1$ set (C, S) Image compression | 32 | 69 6A | 0.1 0.2 |
| TIR-0×09 | Take6 (Moving object) | $M = 32 \times 16$ set (C, S, A) Image compression | 288 | 69 6A 6F | 1.6 3.2 0.1 |
| TIR-0×0A | Take5 (Moving object) | $M = 32 \times 4$ set (C, S, A) Image compression | 96 | 69 6A 6F | 0.4 0.8 0.1 |
| TIR-0×0B | Take7 (SCI tracking) | $M = 16, \times 1$ (C), 30 (S), 1 (C) Image compression | 384 | 69 6A | 3.0 0.4 |
| TIR-0×0C | Take4 (Close-up) | $M = 32 \times 1$ set (C, S) Image compression | 32 | 69 6A | 0.1 0.2 |
| TIR-0×0D | Shutter close | Shutter close for safe | 32 | NA | NA |
| TIR-0×0E | Take8 (HP observations) | $M = 128 \times 4$ set (C, S) 1 for full, 3 for eq. only Image compression | 96 | 69 6A | 0.13 0.8 |
| TIR-0×0F | Take9 (Low altitude) | $M = 32 \times 4$ set(C, S) 1 for full, 3 for eq. only Image compression | 96 | 69 6A | 0.13 0.8 |
| TIR-0×10 | Shut-off TIR | Shutoff sequence | 6 | NA | NA |
| TIR-0×11 | OBS Sequence (Descent) | $4 \times$ TIR-0×0E per 512 s Image compression | 1532 | 69 6A | 0.52 3.2 |

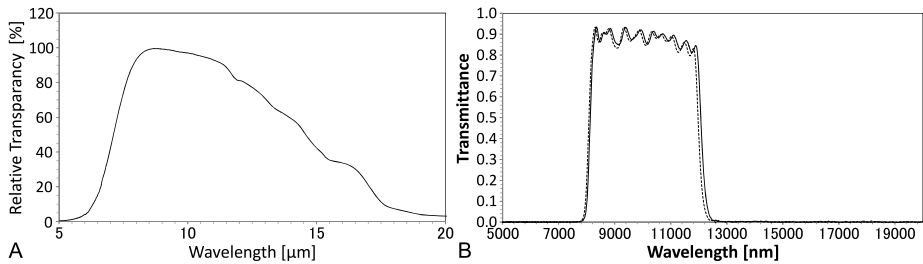


Fig. 11 The detection transparency of TIR is shown. **(A)** The combined transparency of 3 pieces of germanium lens relative to the peak at 8.5 μm is shown as the function of wavelength. **(B)** Transparency function of the band-pass filter is shown for different angular conditions. The solid line shows the angle of incidence (aoi) = 0° and half cone angle (HCA) = 7° , while the dashed line denotes the transparency for aoi = 16.4° and HCA = 21°

5 Performance of TIR

5.1 Wavelength Range

The TIR detection wavelength is determined by the combined transparency of 3 pieces of germanium lens, the detector package, as well as that of the band-pass filter mounted in front of the detector. Figure 11A shows the relative transparency of the germanium lens from 5 to 20 μm with respect to transparency at 8.5 μm . Relative transparency is higher than 80 % from 8 to 12 μm , although there is a tendency towards lower transparency for longer wavelengths. The commercial-based detector package is specifically designed for the 8–12 μm band.

The transparency function of the band-pass filter is almost of rectangular shape, with sharp cut-offs on either side of the 7.9–12.1 μm band. In Fig. 11B, the solid line denotes the transparency spectrum for angle of incidence (aoi) = 0° and half cone angle (HCA) = 7° , while the dashed line shows the transparency spectrum for aoi = 16.4° and HCA = 21° . Both profiles are almost the same, and the angular dependency is very small. This filter pattern is also considered for one of the filters on MARA on MASCOT (Helbert et al. 2014; Grott et al. 2016).

5.2 Fields of View and Image Distortion

Fields of view and image distortion of TIR are estimated using landscape images. In the attitude control test room in the ISAS satellite center (Building-C), TIR observed the geometric structures inside the room on 7 February 2014. One of the TIR images is shown in Fig. 12, a non-summed image using the DE simulator device. In this case, the dimensions of the geometric structures are known. The distance between each vertical pole of the veranda, W , is 0.900 m, which corresponds to 48 ± 1 pixels. Here we took the $4W$ distance, corresponding to 194 ± 1 pixels. The distance from the position of the lens of TIR to the structures was measured with a portable laser range finder as 20.782 ± 0.001 m. The angular resolution of TIR or IFOV is derived as 0.018557 ± 0.000096 m/pixel around the central area of a TIR image, which corresponds to 0.891 ± 0.009 mrad/pixel or $0.051 \pm 0.001^\circ$ /pixel.

The image distortion of TIR is verified by checking the linearity of each linear structure of geometric features and the parallelism between linear structures in this image. All the handrails in the horizontal direction show a good linearity within 1 pixel uncertainty for a length more than 250 pixels (examples are shown as the four dashed white lines in Fig. 12).

Fig. 12 TIR image of geometric structures in the test facility. The dimensions of those structures are known so that IFOV and FOV is determined using the distance from TIR measured with a laser range finder. The image distortion is also verified as negligibly small using the parallelism of handrails (four *dashed white horizontal lines*) at a variety of positions in this image

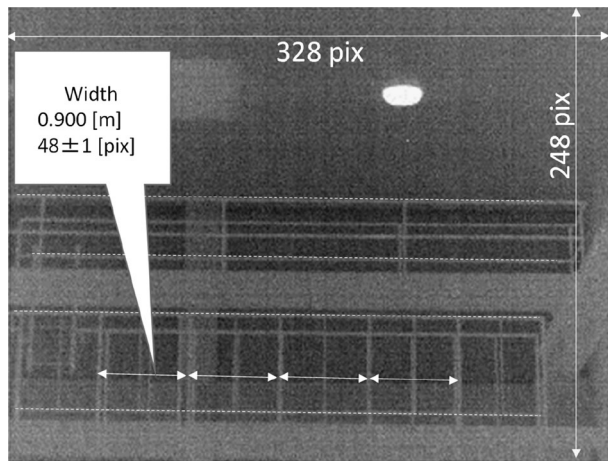


Table 11 IFOV and FOV of TIR

| | |
|------|--|
| IFOV | 0.891 ± 0.009 mrad/pixel or $0.051 \pm 0.001^\circ$ /pixel |
| FOV | $16.74 \pm 0.17^\circ \times 12.66 \pm 0.13^\circ$ |

The parallelism between handrails is also complete within 1 pixel uncertainty. The image distortion is also checked by the negligible difference between the distances of each vertical pole of the veranda. Thus we concluded that the image distortion is negligibly small. So the total FOV can be geometrically calculated as $16.74 \pm 0.17^\circ$ for the horizontal 328 pixels and $12.66 \pm 0.13^\circ$ for the vertical 248 pixels, respectively. Those results are summarized in Table 11.

The results of a more detailed geometrical calibration that was performed using the collimator set in the laboratory will be reported in future papers.

5.3 Temperature Detection Range

TIR's temperature detection range has been tested and calibrated in the laboratory, during system tests, and in space. Since the surface temperature of asteroid Ryugu is estimated to typically range from 250 to 400 K during daytime and down to 150 K during nighttime, it is difficult to calibrate the performance of radiation detectability of TIR using a single type of apparatus. Thus TIR was tested and calibrated with multiple apparatuses and test situations as shown in Table 12. The cross calibration between the apparatuses are needed and such work is in progress now. Detailed descriptions on calibration tests and the apparatuses will be reported in separate papers.

As for the cold target, the blackbody plate in the space chamber was selected because it is in a similar temperature region used for Akatsuki (Planet-C) mission calibration so that the same apparatus was used (Fukuhara et al. 2011). In this system, a blackbody target plate with homogeneous temperature (within 0.3 K) is set in front of TIR-S and the entire field of view is covered by the target plate. The plate is monitored within 0.1 K accuracy at several points. This apparatus was originally built only for the cold temperature range, but by introducing an additional cooling system for TIR-S with silicone oil, the applicable temperature range was successfully extended to ambient temperature.

As a hot target, a commercial-based cavity blackbody was mainly used during the basic performance check. Note that there is a degree of uncertainty in the monitored temperature

Table 12 The apparatus and their temperature ranges

| Test apparatus and test situation | Temperature range | Remarks |
|--|-------------------|--|
| Oil-bath blackbody | 300 to 398 K | Defocused, high stability, accuracy, homogeneity |
| Cavity black body | 300 to 423 K | Defocused, easy to use, some uncertainty in T |
| Collimator with blackbody with peltier control | 293 to 383 K | Focused, High stability, geometrical calibration |
| Blackbody plate in space chamber | 233 to 293 K | Defocused, uneasy for T control |
| System thermal vacuum test (IR panel) | 163 to 178 K | Defocused, rough temperature |
| In-flight operation (during cruise) | <160 K | Deep sky survey |

and the temperature homogeneity in the cavity. Next, an oil-bath blackbody apparatus was developed. The blackbody of this system shows a highly homogeneous temperature distribution and the temperature is well monitored within 0.1 K uncertainty from ambient to hot temperatures up to 423 K (150°C). However, as a result of the influence of thermal emission from the oil-bath, the maximum temperature was limited below 383 K (125°C) at that time. The oil-bath blackbody apparatus was also used for the cross-calibration of TIR with MARA on MASCOT. We also used the collimator system (IR System Co., METS L-10-2.9) but only for a limited number of temperatures, although the accuracy and stability of the blackbody temperature has been proven high enough. The collimator system was mainly used for geometrical calibration using patterned targets due to the limited time available until TIR delivery to the Hayabusa2 final test.

TIR's calibration was originally planned for observations of the sunlit region of asteroid Ryugu, but in order to confirm the noise level of the TIR-S, that is, the lowest temperature TIR can measure, we took some test situations to obtain data using lower temperature targets. The first one was during the system thermal vacuum test, where TIR-S viewed the black body IR panel about 1 m in front of TIR-S. The IR panel temperature was monitored at many points with 0.5 K accuracy, and we estimated the temperature of the IR panel with approximately 1 K uncertainty. The temperature ranged from 163 K to 178 K during the time TIR was tested using the pre-loaded OFPN data. However, at that time it was still unclear whether the lowest temperature measured at that time would be above the noise level.

After Hayabusa2 had been launched, TIR observed the deep sky, whose temperature should be lower than the detection level, and we regarded the data as the TIR-S system noise level. Indeed, we found that the values observed during deep sky observations were significantly lower than those for the IR panel during the system thermal vacuum test. Now we are able to conclude that the temperature at 160 K during the system vacuum test was effectively detected, and that the detection range is more likely to extend down to 150 K.

Figure 13A shows the intensity for various temperatures taken by TIR. These values are taken from the average of 50 x 50 pixels in the central region of 128 frame-summed TIR images. As pointed out above, a single TIR image is 12-bit resolution but becomes 15-bit data after summation in the pre-buffer in DE and bit-shifted for software data processing in DE. In this graph the intensity is shown as 12-bit data, divided by 8, for comparison with the non-summed single image data. We plot the deep sky at 100 K, as we do not know its

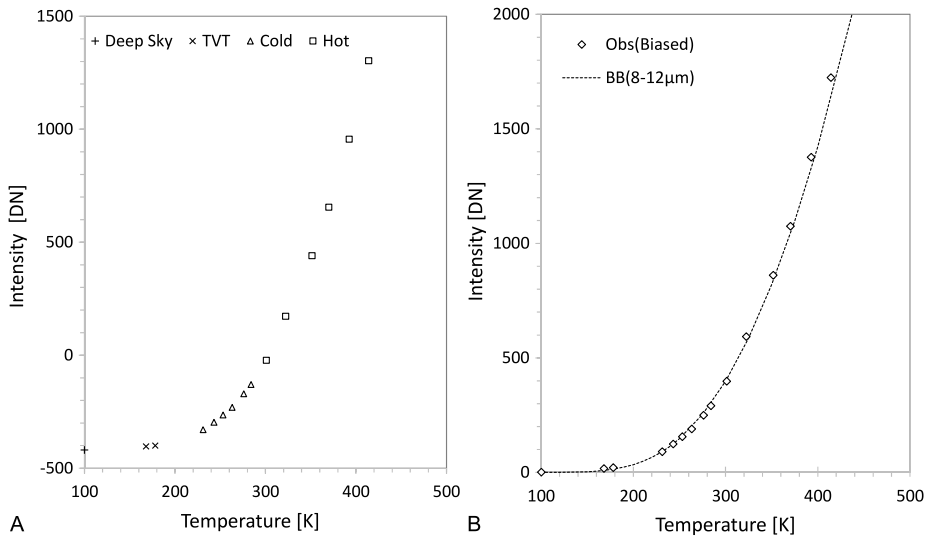


Fig. 13 Temperature detected by TIR using multiple apparatuses and opportunities. TIR calibration was conducted for Cold and Hot conditions using the apparatuses in the laboratory. Colder temperatures were detected during the system TVT test and the deep sky observations in space (A). A best fit line for the 8–12 μm range of blackbody radiation is shown along with the observed intensities which are biased by 421 DN so that the biased intensity is set to 1 at 100 K (B)

exact temperature which, nevertheless, can be expected to be lower than the IR panel in the system TVT test.

In Fig. 13B, we replot all the data with 421 DN biased and also show the calculated relative intensity of blackbody radiation (Planck Function) in 8–12 μm wavelength range. The biased intensity plots of TIR images and the calculated blackbody radiation fit well, at least for the temperature range of 230 K or higher. This fact implies that the thermal infrared detection of TIR is performed well and the system noise level is small ($<$ a few DN) to fit the well-calibrated range at 230 K or above.

The system noise level of TIR still remains somewhat uncertain, but examples of the system noise level of 1 or 10 DN are shown in Fig. 14A and B, respectively, where the vertical axes are logarithmic. Vertical error bars of ± 3 DN are shown in each plot because this is the typical dispersion of a 128-summed image. Apparently the intensities observed during the system TVT tests do not well fit with the blackbody radiation, but are consistent within the error bar.

5.4 Temperature accuracy

The absolute temperature accuracy of commercial thermal infrared imagers is typically 2 or 3 K due to the frame-to-frame dispersion of the bias. This is also the case for TIR when TIR takes a single image. The bias of all the pixels typically changes by several digits, corresponding to 3 K at maximum. We did not find a way to reduce this dispersion. Therefore it is practical to take multiple images. The sum of 128 images has a smaller dispersive bias offset than non-summed images. This is typically within ± 1 K for most of the temperature detection range. It is more practical to take several summed images. For this purpose, we prepare the OPs of TIR-0 \times 0E and TIR-0 \times 0F with a full image and three equatorial region

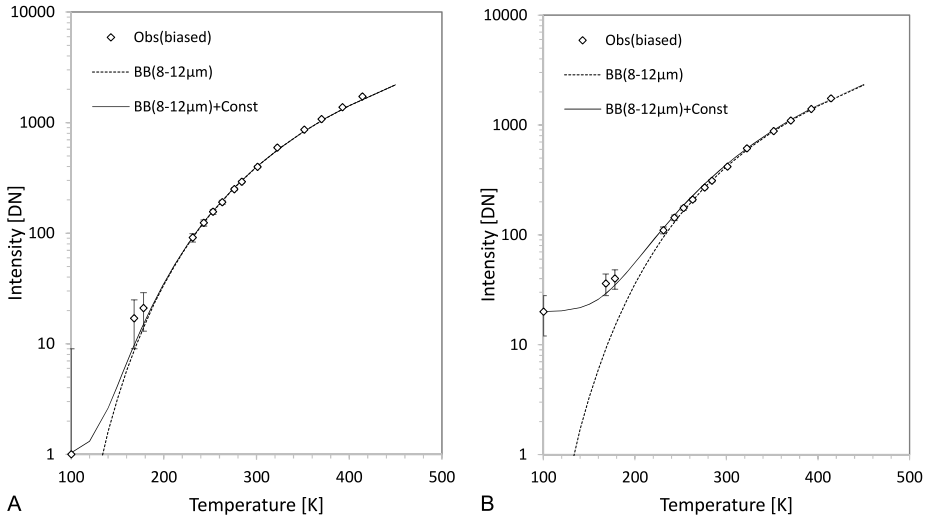
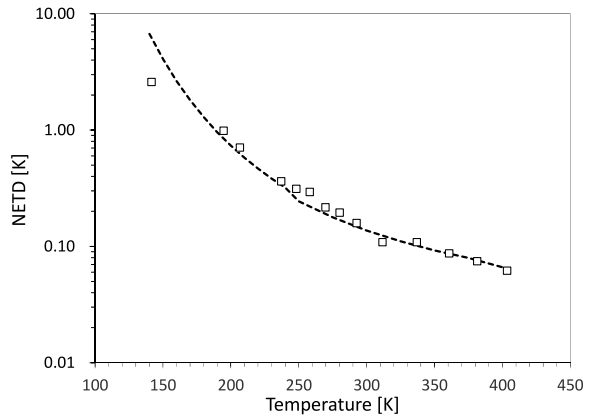


Fig. 14 The data shown in Fig. 13 plotted on a logarithmic scale, along with the blackbody radiation at 8–12 μm . The noise level is assumed for the case of **A** and **B**, respectively

Fig. 15 NETD of the center area of TIR images, with *open squares* denoting the NETD derived from the relation of target temperature difference to the output value difference. The *dashed line* shows the calculated values assuming the values of TIR images are proportional to the band pass region of blackbody radiation energy and the noise level equals 1 digit level for non-summed images (or maximum 8 digits for summed images)



images of 128 and 32 summed images, respectively. The equatorial region image covers 16 instead of 256 vertical pixels only to check the dispersion of bias. The temperature dependence of the absolute temperature is basically compensated using the shutter temperature as reference and by monitoring the temperatures in TIR-S with 0.01 K accuracy.

In spite of the change of absolute temperature, the relative temperature in an image is not influenced by the bias change. Here, we take the relative temperature as noise-equivalent temperature difference (NETD) for the temperature dispersion at the same pixel in a time series. In this case the NETD must be defined for each pixel. Figure 15 shows the averaged values of NETD in the central region of TIR images as a function of target temperature. The open square mark denotes the NETD at the average data points plotted in Fig. 14, and the dashed line shows the calculated curves assuming that TIR values are proportional to the detection range (8 to 12 μm band pass) of blackbody radiation (Planck equation). This result shows that the NETD is 0.3 or 0.4 K or less for >230 K, and the 1 - σ noise level

Table 13 Outline of TIR operation in Hayabusa2 mission

| Phase | Operation contents |
|---------------------|---|
| Launch | Shutter-close to avoid direct sunshine |
| Initial operation | Check the functionality and basic performance after launch |
| Transfer and EDVEGA | Health and performance check by taking deep sky images → A long-term trend of degradation and a dependency of temperature Earth and Moon observations during Earth Swing-by → Alignment and radiometric check using Earth and Moon |
| Approach | Asteroid light-curve and radiometric measurements → Direct comparison with ground based observations Moon search, and observations of environmental dust clouds |
| Rendezvous | HP (~20 km altitude): Global thermal imaging of asteroid → Construct a global thermo-physical model (~20 m/pixel) XO (~20 km, high phase angle): observations for polar and dawn-dusk regions → Complete the global thermo-physical model addition to HP observations MA (~5 km mid altitude): Global TPM with higher resolution mapping (3–5 m/pixel) → Determine the TD site and geological context for the landed sites LA (~1 km altitude): local site thermal imaging → TD and landers site context (1 m/pixel) Close-up (10–1000 m altitude): highest resolution images during the descent Landers landing site search after deploy (0.1–1 km altitude) SCI tracking (500 m altitude): consecutive imaging of SCI SCI crater search and observation (1 km or lower): SCI impact points |

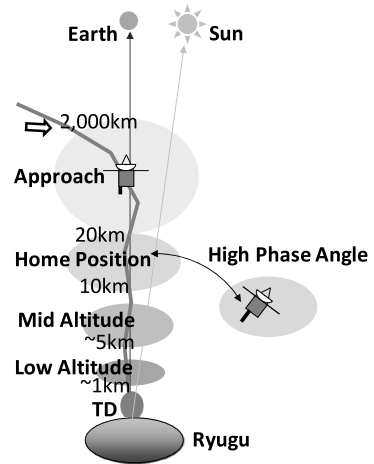
is about 1 digit for summed images. In the lower temperature range, the NETD becomes worse but remains within several K. A detailed calibration has been done, especially for the cross calibration between the apparatuses, so that more precise NETD will be reported in a separate paper both with regard to time series of each pixel and spatial region.

6 Observation Plan of TIR

6.1 Outline of TIR Operation Plan

The plan of TIR operations during the asteroid rendezvous phase is outlined in Table 13, and the schematic diagram is shown in Fig. 16. In order to avoid direct irradiation of sunshine into the TIR detector, TIR closed the shutter by command just after the separation of Hayabusa2 from the launch vehicle during the launch operation. During the initial function check on 11 December 2014, TIR checked its functionality using the quick check OP (TIR-0×02), which was also used during the system environmental tests. For the performance test on 17 December 2014, TIR checked its performance using the health check OP (TIR-0×05) with the temperature conditions adjusted using the HCE parameter settings by command. During the pre-flight test, we have learned that Shutter and Case temperatures should be stable as much as possible and set higher than 299.5 K and 300.0 K, respectively. To achieve this condition, the Lens temperature (Channel 60A) and the Panel temperature (Channel 61A) both controlled by HCE should be adjusted at slightly higher setting points than those for the preservation (300.5 K and 298.0 K, respectively). So far we find that setting points that are 1.5 K higher for both channels show good results.

Fig. 16 The schematic diagram of the configuration of Hayabusa2 positions at the asteroid rendezvous phase is shown. Hayabusa2 will approach the asteroid from the sunward direction, mainly operated at the Home Position. The spacecraft will descend to the lower altitude for mission purposes



The health check will be continued once every month, and at the beginning of each operation phase. The observation plan will be presented in Sects. 6.2 to 6.7.

6.2 Observation During Cruise and Earth Swing-By

TIR will observe the deep sky once every month to conduct its health check using the health check OP (TIR-0×05), to adjust the temperature conditions by HCE parameter settings, and to trace the possible degradation of the detector during the 3.5-year long cruise phase. The deep sky is considered a good target since it can be used as a kind of flat field cold target to estimate the noise level and check anisotropic response.

Just before and after the Earth swing-by, TIR is planned to image the Earth and the Moon using the health check OP (TIR-0×05). One of the objectives is an alignment check with ONC and the attitude control of the Hayabusa2 spacecraft. When TIR observes the Earth and the Moon in an image concurrently with a wide angle camera (ONC-W1) or a telescopic camera (ONC-T), which is possible 30 to 10 days before the Earth swing-by, the alignment ($-Z$ direction and roll angle of Hayabusa2 spacecraft) can be checked within a pixel accuracy. The other objectives of the observation are to measure the thermal radiation from the Earth or the Moon, since they are the only targets with known temperatures during the mission. Just after the Earth swing-by, TIR will observe the Earth and the Moon at closer distance using the health check OP (TIR-0×05) or low-altitude OPs (TIR-0×0A and TIR-0×0C).

6.3 Observation whilst Approaching the Asteroid (AP)

TIR will measure thermal infrared intensity and light-curves during the spacecraft's approach towards asteroid Ryugu and compare them with the results from ground-based observations. The asteroid is about the size of 1 pixel or less at a distance of 2000 km to 1000 km from the asteroid. We plan to take more than 20 images using the HP OP (TIR-0×0E) during an asteroid rotation of 7.63 hours. After this phase, the asteroid becomes larger than 1 pixel so that we start observations not only for thermal emission but also for constructing shape models. At a distance of 100 km or closer to the asteroid, TIR will also observe the surrounding dust clouds and orbiting moons using the HP OP (TIR-0×0E) or long exposure

moving object OP (TIR-0×09). In case they are made of carbonaceous chondrite material, any moons are expected to be detected if larger than 1/5 pixel in size. For example, this translates to 20 m object size for 100 km distance.

6.4 Observations at Home Position (HP) and at Large Phase Angles (XO)

After the arrival of the Home Position, about 20 km earthward from the asteroid, TIR will observe the asteroid once a week, by taking images using the HP OP (TIR-0×0E) every 512 seconds during an asteroid rotation of 7.63 hours. More than 50 images are taken during one asteroid rotation. This is to be used to construct a thermal model with an improved thermal inertia compared to the one derived from a single thermal image. The thermal model of the whole asteroid will be constructed as the final product in this phase, with a spatial resolution of typically 17 m per pixel. A preliminary asteroid thermal model will be constructed sooner, probably in a week, for operational use. This model will be used to avoid hazardous operations by estimating the surface thermal environment during descent operations of the spacecraft, as well as assessing the distribution of boulders at the candidate sites on the asteroid.

A detailed asteroid thermal model constructed for scientific use will be available in a month, but updated according to updates of the asteroid shape model and the position and attitude of spacecraft. Due to the change of distance from the sun from 0.96 to 1.42 AU, the long-term trend of temperature change will be obtained and the thermal inertia resulting from thicker skin depths will be investigated. This model will be used for dedicated scientific studies and to constrain the surface particle size or possible existence of organics to select the landing sites of the mission.

Observations from large phase angles will also be planned. This phase is needed to map the entire surface completely and to obtain observations at different, higher phase angles. In particular for TIR, not only the polar region but the dawn and dusk regions could be easily observed. Since temperatures at the dawn and dusk regions are sensitive to the surface thermal inertia, as shown in Fig. 1, these observations are important to investigate thermal inertia.

6.5 Lower Altitude Observations (MA, LA)

Before the descent operations for sample collection or deployment of landing robots, the spacecraft will descend to a lower altitude and observe the candidate sites in more detail to confirm whether the sites are suitable with regard to scientific and mission requirements. One or two asteroid rotations (7.63 and 15.26 hours) before arrival at target altitude, TIR will image the surface using the descent OP (TIR-0×11). At 5 km altitude (MA), TIR will take images using the moving object OP (TIR-0×0C) every 512 or 256 seconds and map the hemisphere including the candidate sites with 4.3 m spatial resolution. These images are used to confirm the thermal model constructed beforehand, and also to construct a more detailed thermal model.

At 1 km altitude (LA), TIR will take images of specific sites at 85 cm per pixel and 280×210 m area, probably in an hour, using the moving object OP (TIR-0×0C). Geologic features are imaged at proper intervals and investigated for their thermo-physical properties.

6.6 Descent, Close-Up, and Touchdown Observations (CU, TD)

For sample collection, or deployment of landing robots, as well as their rehearsals, the spacecraft will descend to a lower altitude. Again, 1 or 2 asteroid rotations (7.63 and 15.26 hours)

before the arrival at the target sites, TIR will image the surface using the descent OP (TIR-0×11). At a lower altitude between 1 km and 50 m, TIR will also observe the surface of the asteroid at a higher spatial resolution using the moving object OP (TIR-0×0C) every 256 second nominally.

For the final descent from 50 m to 5 m altitude, TIR will image the surface using the moving object OP (TIR-0×0C) more frequently, namely every 60 seconds. The final spatial resolution is an order of centimeters. TIR will stop its observations using the shutoff OP (TIR-0×10) at 5 m altitude just before the start of the free fall of the spacecraft for touchdown.

For the deployment of landing robots such as MINERVA-II and MASCOT, the altitude of deployment will be about 60 m. TIR will image the landing sites using the moving object OP (TIR-0×0C). After deployment, the spacecraft will ascend to 3 km altitude and hover at altitude for 24 hours, then ascend to HP. TIR will observe the asteroid surface using the moving object OP (TIR-0×0C) every 512 seconds nominally.

6.7 SCI Separation and SCI Search

For the SCI separation, the spacecraft will descend to 500 m altitude, deploy SCI, and escape from there to the safe area behind the asteroid. Again, 1 or 2 asteroid rotations (7.63 and 15.26 hours) before the arrival of target sites, TIR will image the surface using the descent OP (TIR-0×11). At the altitude of 1 km to 500 m, TIR will image the surface using the moving object OP (TIR-0×0C). Just after separation of SCI, TIR will take images of SCI using the SCI tracking OP (TIR-0×0B), 30 images for each 2-second interval. After escape from there and behind the asteroid, TIR will observe the dust stream originating from the surface of asteroid excavated by the SCI impact, using the long exposure moving object OP (TIR-0×09).

7 Summary

TIR is the thermal infrared imager on Hayabusa2 designed to map the thermo-physical properties of C-type near-Earth asteroid 162173 Ryugu. We have demonstrated the scientific importance of thermal infrared imaging and presented the scientific and mission objectives. The specifications of TIR have been described, showing that TIR has a relatively wide field of view of $16 \times 12^\circ$ to image the thermal emission from the asteroid and also covers a wide temperature range of 150 K to 460 K with 230–420 K as the well-calibrated range. The performance meets scientific and system requirements. Detailed instrumentation and data processing flows have been shown. A detailed operation plan was also given for launch, cruise, home position and low-altitude operations. The thermal model obtained from TIR data will contribute to understanding the nature of the target asteroid and will also be valuable for sampling site selection and landing safely.

Acknowledgements We appreciate all the members of Hayabusa2 project for scientific and technical support for the development and operation of TIR. This research is partly supported by the Grant-in-Aid for Scientific Research (B), No. 26287108, of the Japan Society for the Promotion of Science.

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